**Scanner**

scanLights();  
calculateBearings();  
getDistanceToWall();  
getDistance();  
rotateTo();  
getHeadAngle();  
getBearings();

**Pose**

setLocation();  
setHeading();  
getX();  
getY();  
getLocation();  
getHeading();  
relativeBearing();

**Locator**

scanBeacon();  
locate();  
fixPosition();  
normalize();

**DifferentialPilot**

setAcceleration();  
setTravelSpeed();  
setRotationSpeed();

**Milestone3**

Main();

**DataLogger**

writeLog();  
transmit();

**NXTRegulatedMotor**

**LightSensor**

**UltrasonicSensor**